

# 3.3 V, 100 Mbps, Half- and Full-Duplex, High Speed M-LVDS Transceivers

**Data Sheet** 

ADN4690E/ADN4692E

#### **FEATURES**

Multipoint LVDS transceivers (low voltage differential signaling driver and receiver pairs) Switching rates: 100 Mbps (50 MHz) Supported bus loads: 30  $\Omega$  to 55  $\Omega$ 

Type 1 receiver (ADN4690E/ADN4692E): hysteresis of 25 mV

Conforms to TIA/EIA-899 standard for M-LVDS
Glitch-free power-up/power-down on M-LVDS bus
Controlled transition times on driver output
Common-mode range: -1 V to +3.4 V, allowing
communication with 2 V of ground noise

Driver outputs high-Z when disabled or powered off

**Enhanced ESD protection on bus pins** 

±15 kV HBM (human body model), air discharge

 $\pm 8$  kV HBM (human body model), contact discharge

±10 kV IEC 61000-4-2, air discharge ±8 kV IEC 61000-4-2, contact discharge

Operating temperature range: -40°C to +85°C

Available in 8-lead (ADN4690E) and 14-lead (ADN4692E)

**SOIC** packages

#### **APPLICATIONS**

Backplane and cable multipoint data transmission
Multipoint clock distribution
Low power, high speed alternative to shorter RS-485 links
Networking routers and switches
Wireless base station infrastructure

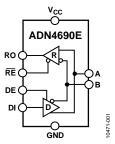
#### **GENERAL DESCRIPTION**

The ADN4690E/ADN4692E are multipoint, low voltage differential signaling (M-LVDS) transceivers (driver and receiver pairs) that can operate at up to 100 Mbps (50 MHz). To improve the integrity of the output signal and minimize reflections, slew rate control is implemented on the driver outputs. The receivers detect the bus state with a differential input of as little as 50 mV over a common-mode voltage range of  $-1~\rm V$  to  $+3.4~\rm V$ . ESD protection of up to  $\pm15~\rm kV$  is implemented on the bus pins.

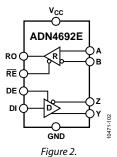
The ADN4690E/ADN4692E adhere to the TIA/EIA-899 standard for M-LVDS and complement TIA/EIA-644 LVDS devices with additional multipoint capabilities. The driver allows bus loads of as little as 30  $\Omega$  on a multipoint bus topology, and driver output transition times are controlled to minimize reflections. Up to 32 nodes can be connected to the bus.

The ADN4690E/ADN4692E are Type 1 receivers that are designed to have 25 mV of hysteresis on the differential input

#### **FUNCTIONAL BLOCK DIAGRAMS**



Fiaure 1.



voltage, so that slow-changing signals or a loss of input does not lead to output oscillations.

The ADN4690E/ADN4692E are available as half-duplex configurations in an 8-lead SOIC package (the ADN4690E) or as full-duplex configurations in a 14-lead SOIC package (the ADN4692E). A selection table for the ADN469xE parts is shown in Table 1.

Table 1. ADN469xE Selection Table

Part No.	Receiver Type	Data Rate	SOIC Package	Half-/Full- Duplex
ADN4690E	Type 1	100 Mbps	8-lead	Half
ADN4692E	Type 1	100 Mbps	14-lead	Full
ADN4696E	Type 2	200 Mbps	8-lead	Half
ADN4697E	Type 2	200 Mbps	14-lead	Full

# ADN4690E/ADN4692E

# **Data Sheet**

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### **REVISION HISTORY**

2/12—Revision 0: Initial Version

# **SPECIFICATIONS**

 $V_{\text{CC}}$  = 3.0 V to 3.6 V;  $R_{\text{L}}$  = 50  $\Omega;$   $T_{\text{A}}$  =  $T_{\text{MIN}}$  to  $T_{\text{MAX}}$ , unless otherwise noted.  $^{1}$ 

Table 2.

Parameter	Symbol	Min	Тур	Max	Unit	<b>Test Conditions/Comments</b>
DRIVER						
Differential Outputs						
Differential Output Voltage Magnitude	V <sub>OD</sub>	480		650	mV	See Figure 18
Δ V <sub>OD</sub>   for Complementary Output States	Δ V <sub>OD</sub>	-50		+50	mV	See Figure 18
Common-Mode Output Voltage (Steady State)	V <sub>OC(SS)</sub>	0.8		1.2	V	See Figure 19, Figure 22
ΔV <sub>OC(SS)</sub> for Complementary Output States	$\Delta V_{OC(SS)}$	-50		+50	mV	See Figure 19, Figure 22
Peak-to-Peak Voc	V <sub>OC(PP)</sub>			150	mV	See Figure 19, Figure 22
Maximum Steady-State Open-Circuit Output Voltage	V <sub>A(O)</sub> , V <sub>B(O)</sub> , V <sub>Y(O)</sub> , or V <sub>Z(O)</sub>	0		2.4	V	See Figure 20
Voltage Overshoot, Low to High	$V_{PH}$			<b>1.2V</b> ss	V	See Figure 23, Figure 26
Voltage Overshoot, High to Low	$V_{PL}$	-0.2V <sub>SS</sub>			V	See Figure 23, Figure 26
Output Current						
Short Circuit	Ios			24	mA	See Figure 21
High Impedance State, Driver Only	loz	-15		+10	μΑ	$-1.4 \text{ V} \le (V_Y \text{ or } V_Z) \le 3.8 \text{ V},$ other output = 1.2 V
Power Off	lo(OFF)	-10		+10	μΑ	$-1.4 \text{ V} \le (V_Y \text{ or } V_Z) \le 3.8 \text{ V},$ other output = 1.2 V, $0 \text{ V} \le V_{CC} \le 1.5 \text{ V}$
Output Capacitance	C <sub>Y</sub> or C <sub>Z</sub>		3		pF	$V_1 = 0.4 \sin(30e^6\pi t) V + 0.5 V$ , other output = 1.2 V, DE = 0 V
Differential Output Capacitance	C <sub>YZ</sub>			2.5	рF	$V_{AB} = 0.4 \sin(30e^6\pi t) V_{,2} DE = 0 V_{,2}$
Output Capacitance Balance (C <sub>Y</sub> /C <sub>Z</sub> )	C <sub>Y/Z</sub>	0.99		1.01		
Logic Inputs, DI, DE						
Input High Voltage	V <sub>IH</sub>	2		$V_{CC}$	V	
Input Low Voltage	V <sub>IL</sub>	GND		8.0	V	
Input High Current	I <sub>IH</sub>	0		10	μΑ	$V_{IH} = 2 V \text{ to } V_{CC}$
Input Low Current	I <sub>IL</sub>	0		10	μΑ	$V_{IL} = GND$ to 0.8 V
RECEIVER						
Differential Inputs						
Differential Input Threshold Voltage						
Type 1 Receiver (ADN4690E, ADN4692E) Input Hysteresis	V <sub>TH</sub>	-50		+50	mV	See Table 3, Figure 35
Type 1 Receiver (ADN4690E, ADN4692E)	V <sub>HYS</sub>		25		mV	
Differential Input Voltage Magnitude	V <sub>ID</sub>	0.05		$V_{CC}$	V	
Input Capacitance	C <sub>A</sub> or C <sub>B</sub>		3		pF	$V_1 = 0.4 \sin(30e^6\pi t) V + 0.5 V_{,2}^2$ other input = 1.2 V
Differential Input Capacitance	Сав	1		2.5	рF	$V_{AB} = 0.4 \sin(30e^6\pi t) V^2$
Input Capacitance Balance (C <sub>A</sub> /C <sub>B</sub> )	C <sub>A/B</sub>	0.99		1.01		
Logic Output RO						
Output High Voltage	V <sub>OH</sub>	2.4			٧	$I_{OH} = -8 \text{ mA}$
Output Low Voltage	V <sub>OL</sub>			0.4	٧	$I_{OL} = 8 \text{ mA}$
High Impedance Output Current	loz	-10		+15	μΑ	$V_0 = 0 \text{ V or } 3.6 \text{ V}$
Logic Input RE		1				
Input High Voltage	V <sub>IH</sub>	2		$V_{CC}$	V	
Input Low Voltage	V <sub>IL</sub>	GND		0.8	V	
Input High Current	IIH	-10		0	μΑ	$V_{IH} = 2 V \text{ to } V_{CC}$
Input Low Current	l <sub>IL</sub>	-10		0	μA	$V_{IL} = GND$ to 0.8 V

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions/Comments
BUS INPUT/OUTPUT						
Input Current						
A (Receiver or Transceiver with Driver Disabled)	IA	0		32	μΑ	$V_B = 1.2 \text{ V}, V_A = 3.8 \text{ V}$
		-20		+20	μΑ	$V_B = 1.2 \text{ V}, V_A = 0 \text{ V or } 2.4 \text{ V}$
		-32		0	μΑ	$V_B = 1.2 \text{ V}, V_A = -1.4 \text{ V}$
B (Receiver or Transceiver with Driver Disabled)	I <sub>B</sub>	0		32	μΑ	$V_A = 1.2 \text{ V}, V_B = 3.8 \text{ V}$
		-20		+20	μΑ	$V_A = 1.2 \text{ V}, V_B = 0 \text{ V or } 2.4 \text{ V}$
		-32		0	μΑ	$V_A = 1.2 \text{ V}, V_B = -1.4 \text{ V}$
Differential (Receiver or Transceiver with Driver Disabled)	I <sub>AB</sub>	-4		+4	μΑ	$V_A = V_B$ , $1.4 \text{ V} \le V_A \le 3.8 \text{ V}$
Power-Off Input Current						0 V ≤ V <sub>CC</sub> ≤ 1.5 V
A (Receiver or Transceiver)	I <sub>A(OFF)</sub>	0		32	μΑ	$V_B = 1.2 \text{ V}, V_A = 3.8 \text{ V}$
		-20		+20	μΑ	$V_B = 1.2 \text{ V}, V_A = 0 \text{ V or } 2.4 \text{ V}$
		-32		0	μΑ	$V_B = 1.2 \text{ V}, V_A = -1.4 \text{ V}$
B (Receiver or Transceiver)	I <sub>B(OFF)</sub>	0		32	μΑ	$V_A = 1.2 \text{ V}, V_B = 3.8 \text{ V}$
		-20		+20	μΑ	$V_A = 1.2 \text{ V}, V_B = 0 \text{ V or } 2.4 \text{ V}$
		-32		0	μΑ	$V_A = 1.2 \text{ V}, V_B = -1.4 \text{ V}$
Differential (Receiver or Transceiver)	I <sub>AB(OFF)</sub>	-4		+4	μΑ	$V_A = V_B$ , $1.4 \le V_A \le 3.8 \text{ V}$
Input Capacitance (Transceiver with Driver Disabled)	C <sub>A</sub> or C <sub>B</sub>		5		pF	$V_1 = 0.4 \sin(30e^6\pi t) V + 0.5 V_1^2$ other input = 1.2 V, DE = 0 V
Differential Input Capacitance (Transceiver with Driver Disabled)	Сав			3	pF	$V_{AB} = 0.4 \sin(30e^6\pi t) \text{ V,}^2 \text{ DE} = 0 \text{ V}$
Input Capacitance Balance $(C_A/C_B)$ (Transceiver with Driver Disabled)	C <sub>A/B</sub>	0.99		1.01		DE = 0 V
POWER SUPPLY						
Supply Current	Icc					
Only Driver Enabled			13	22	mA	DE, $\overline{RE} = V_{CC}$ , $R_L = 50 \Omega$
Both Driver and Receiver Disabled			1	4	mA	$DE = 0 V$ , $\overline{RE} = V_{CC}$ , $R_L = no load$
Both Driver and Receiver Enabled			16	24	mA	$DE = V_{CC}$ , $\overline{RE} = 0 \text{ V}$ , $R_L = 50 \Omega$
Only Receiver Enabled			4	13	mA	DE, $\overline{RE} = 0 \text{ V}$ , $R_L = 50 \Omega$
Total Power Dissipation	P <sub>D</sub>			94	mW	$R_L = 50 \Omega$ , input (DI): 50 MHz, 50% duty cycle square wave; DE = $V_{CC}$ ; $RE = 0 V$ ; $T_A = 85^{\circ}C$

 $<sup>^1</sup>$  All typical values are given for  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C.  $^2$  HP4194A impedance analyzer (or equivalent).

### **RECEIVER INPUT THRESHOLD TEST VOLTAGES**

 $\overline{RE} = 0$  V, H = high, L = low.

Table 3. Test Voltages for Type 1 Receiver

Applied	d Voltages	Input Voltage, Differential	Input Voltage, Common Mode	Receiver Output
V <sub>A</sub> (V)	V <sub>B</sub> (V)	V <sub>ID</sub> (V)	V <sub>IC</sub> (V)	RO
2.4	0	2.4	1.2	Н
0	2.4	-2.4	1.2	L
3.425	3.375	0.05	3.4	Н
3.375	3.425	-0.05	3.4	L
-0.975	-1.025	0.05	-1	Н
-1.025	-0.975	-0.05	<b>-1</b>	L

### **TIMING SPECIFICATIONS**

 $V_{\text{CC}}$  = 3.0 V to 3.6 V;  $T_{\text{A}}$  =  $T_{\text{MIN}}$  to  $T_{\text{MAX}},$  unless otherwise noted.  $^{1}$ 

Table 4.

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions / Comments
DRIVER						
Maximum Data Rate		100			Mbps	
Propagation Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	2	2.5	3.5	ns	See Figure 23, Figure 26
Differential Output Rise/Fall Time	t <sub>R</sub> , t <sub>F</sub>	2	2.6	3.2	ns	See Figure 23, Figure 26
Pulse Skew  tphl - tplh	t <sub>SK</sub>		30	150	ps	See Figure 23, Figure 26
Part-to-Part Skew	t <sub>SK(PP)</sub>			0.9	ns	See Figure 23, Figure 26
Period Jitter, rms (One Standard Deviation) <sup>2</sup>	t <sub>J(PER)</sub>		2	3	ps	50 MHz clock input, <sup>3</sup> see Figure 25
Peak-to-Peak Jitter <sup>2, 4</sup>	t <sub>J(PP)</sub>			150	ps	100 Mbps 2 <sup>15</sup> – 1 PRBS input, <sup>5</sup> see Figure 28
Disable Time from High Level	<b>t</b> <sub>PHZ</sub>		4	7	ns	See Figure 24, Figure 27
Disable Time from Low Level	t <sub>PLZ</sub>		4	7	ns	See Figure 24, Figure 27
Enable Time to High Level	<b>t</b> <sub>PZH</sub>		4	7	ns	See Figure 24, Figure 27
Enable Time to Low Level	t <sub>PZL</sub>		4	7	ns	See Figure 24, Figure 27
RECEIVER						
Propagation Delay	t <sub>RPLH</sub> , t <sub>RPHL</sub>	2		6	ns	$C_L = 15 \text{ pF, see Figure 29, Figure 32}$
Rise/Fall Time	t <sub>R</sub> , t <sub>F</sub>	1		2.3	ns	$C_L = 15 \text{ pF, see Figure 29, Figure 32}$
Pulse Skew  trphl - trplh						
Type 1 Receiver (ADN4690E, ADN4692E)	t <sub>SK</sub>		100	300	ps	$C_L = 15 \text{ pF, see Figure 29, Figure 32}$
Part-to-Part Skew <sup>6</sup>	t <sub>SK(PP)</sub>			1	ns	$C_L = 15 \text{ pF, see Figure 29, Figure 32}$
Period Jitter, rms (One Standard Deviation) <sup>2</sup>	t <sub>J(PER)</sub>		4	7	ps	50 MHz clock input, <sup>3</sup> see Figure 31
Peak-to-Peak Jitter <sup>2, 4</sup>						
Type 1 Receiver (ADN4690E, ADN4692E)	t <sub>J(PP)</sub>		200	700	ps	100 Mbps 2 <sup>15</sup> – 1 PRBS input, <sup>5</sup> see Figure 34
Disable Time from High Level	t <sub>RPHZ</sub>		6	10	ns	See Figure 30, Figure 33
Disable Time from Low Level	t <sub>RPLZ</sub>		6	10	ns	See Figure 30, Figure 33
Enable Time to High Level	t <sub>RPZH</sub>		10	15	ns	See Figure 30, Figure 33
Enable Time to Low Level	t <sub>RPZL</sub>		10	15	ns	See Figure 30, Figure 33

 $<sup>^{\</sup>scriptscriptstyle 1}$  All typical values are given for  $V_{\text{CC}}=3.3~\text{V}$  and  $T_{\text{A}}=25^{\circ}\text{C}.$ 

<sup>&</sup>lt;sup>2</sup> Jitter parameters are guaranteed by design and characterization. Values do not include stimulus jitter.

 $<sup>^3</sup>$   $t_R$  =  $t_F$  = 0.5 ns (10% to 90%), measured over 30,000 samples.  $^4$  Peak-to-peak jitter specifications include jitter due to pulse skew ( $t_{sk}$ ).  $^5$   $t_R$  =  $t_F$  = 0.5 ns (10% to 90%), measured over 100,000 samples.

<sup>&</sup>lt;sup>6</sup> HP4194A impedance analyzer or equivalent.

# **ABSOLUTE MAXIMUM RATINGS**

 $T_A = T_{MIN}$  to  $T_{MAX}$  unless otherwise noted.

Table 5.

1 autc 3.	
Parameter	Rating
V <sub>CC</sub>	-0.5 V to +4 V
Digital Input Voltage (DE, $\overline{RE}$ , DI)	–0.5 V to +4 V
Receiver Input (A, B) Voltage	
Half-Duplex (ADN4690E)	–1.8 V to +4 V
Full-Duplex (ADN4692E)	-4 V to +6 V
Receiver Output Voltage (RO)	–0.3 V to +4 V
Driver Output (A, B, Y, Z) Voltage	–1.8 V to +4 V
ESD Rating (A, B, Y, Z Pins)	
HBM (Human Body Model)	
Air Discharge	±15 kV
Contact Discharge	±8 kV
IEC 61000-4-2, Air Discharge	±10 kV
IEC 61000-4-2, Contact Discharge	±8 kV
ESD Rating (Other Pins, HBM)	±4 kV
ESD Rating (All Pins)	
FICDM	±1.25 kV
Machine Model	±400 V
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	−65°C to +150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL RESISTANCE

 $\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

**Table 6. Thermal Resistance** 

Package Type	θ <sub>JA</sub>	Unit
8-Lead SOIC	121	°C/W
14-Lead SOIC	86	°C/W

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



Figure 3. ADN4690E Pin Configuration

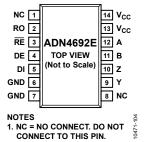


Figure 4. ADN4692E Pin Configuration

#### **Table 7. Pin Function Descriptions**

ADN4690E	ADN4692E		
Pin No.	Pin No.	Mnemonic	Description
1	2	RO	Receiver Output. Type 1 receiver (ADN4690E/ADN4692E), when enabled: if $A - B \ge 50$ mV, then $RO = logic high$ . If $A - B \le -50$ mV, then $RO = logic low$ . Receiver output is undefined outside these conditions.
2	3	RE	Receiver Output Enable. A logic low on this pin enables the receiver output, RO. A logic high on this pin places RO in a high impedance state.
3	4	DE	Driver Output Enable. A logic high on this pin enables the A and B driver differential outputs.  A logic low on this pin places the A and B driver differential outputs in a high impedance state.
4	5	DI	Driver Input. Half-duplex (ADN4690E), when enabled: A logic low on this pin forces A low and B high, whereas a logic high on this pin forces A high and B low. Full-duplex (ADN4692E), when enabled: A logic low on this pin forces Y low and Z high, whereas a logic high on this pin forces Y high and Z low.
5	6, 7	GND	Ground.
N/A	9	Υ	Noninverting Driver Output.
N/A	10	Z	Inverting Driver Output.
6	N/A	Α	Noninverting Receiver Input A and Noninverting Driver Output A.
N/A	12	Α	Noninverting Receiver Input A.
7	N/A	В	Inverting Receiver Input B and Inverting Driver Output B.
N/A	11	В	Inverting Receiver Input B.
8	13, 14	Vcc	Power Supply (3.3 V $\pm$ 0.3 V).
N/A	1, 8	NC	No Connect. Do not connect to this pins.

# TYPICAL PERFORMANCE CHARACTERISTICS

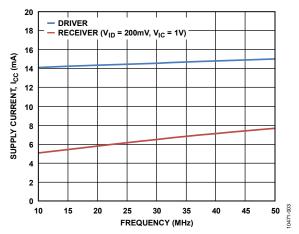


Figure 5. Power Supply Current ( $I_{CC}$ ) vs. Frequency ( $V_{CC} = 3.3 \text{ V}, T_A = 25^{\circ}\text{C}$ )

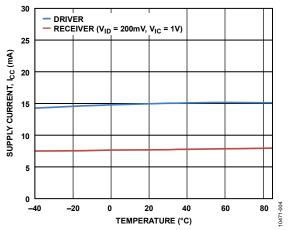


Figure 6. Power Supply Current vs. Temperature (Data Rate = 100 Mbps,  $V_{CC} = 3.3 \text{ V}$ )

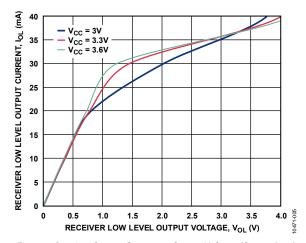


Figure 7. Receiver Output Current vs. Output Voltage (Output Low)  $(T_A = 25^{\circ}C)$ 

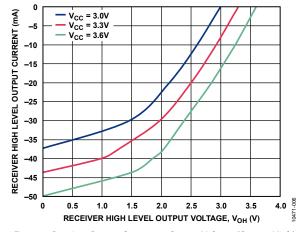


Figure 8. Receiver Output Current vs. Output Voltage (Output High)  $(T_A = 25^{\circ}C)$ 

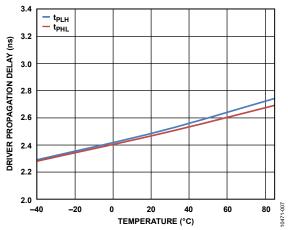


Figure 9. Driver Propagation Delay vs. Temperature (Data Rate = 2 Mbps,  $V_{CC}$  = 3.3 V,  $R_L$  = 50  $\Omega$ )

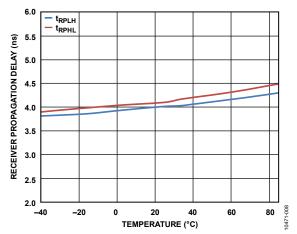


Figure 10. Receiver Propagation Delay vs. Temperature (Data Rate = 2 Mbps,  $V_{CC}$  = 3.3 V,  $V_{ID}$  = 200 mV,  $V_{IC}$  = 1 V,  $C_L$  = 15 pF)

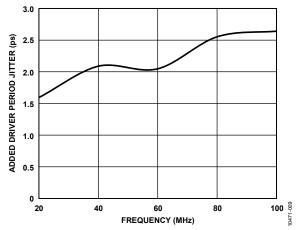


Figure 11. Driver Jitter (Period) vs. Frequency  $(V_{CC} = 3.3 V, T_A = 25^{\circ}C, Clock Input)$ 

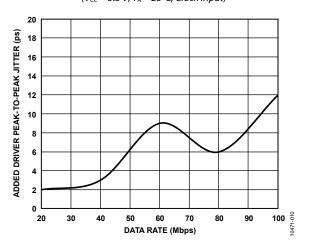


Figure 12. Driver Jitter (Peak-to-Peak) vs. Data Rate  $(V_{CC} = 3.3 \text{ V}, T_A = 25^{\circ}\text{C}, PRBS 2^{15} - 1 \text{ NRZ Input})$ 

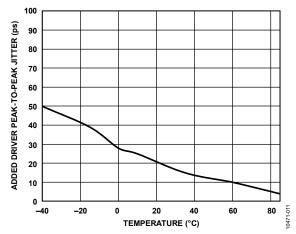


Figure 13. Driver Jitter (Peak-to-Peak) vs. Temperature (Data Rate = 100 Mbps,  $V_{CC}$  = 3.3 V,  $T_A$  = 25°C, PRBS  $2^{15}$  – 1 NRZ Input)

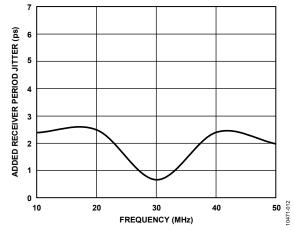


Figure 14. Receiver Jitter (Period) vs. Frequency ( $V_{CC} = 3.3 \text{ V}$ ,  $T_A = 25 ^{\circ}\text{C}$ ,  $V_{IC} = 1 \text{ V}$ , Clock Input)

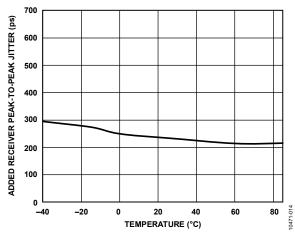


Figure 15. Receiver Jitter (Peak-to-Peak) vs. Temperature ( $V_{CC} = 3.3 \text{ V}, V_{IC} = 1 \text{ V}, PRBS 2^{15} - 1 \text{ NRZ Input}$ )

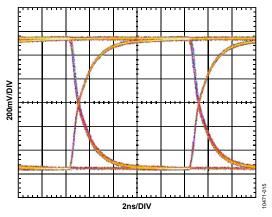


Figure 16. ADN4690E Driver Output Eye Pattern (Data Rate = 100 Mbps, PRBS  $2^{15}$  – 1 Input,  $R_L$  = 50  $\Omega$ )

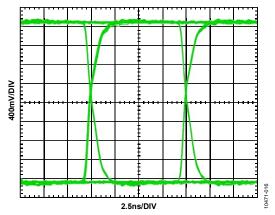


Figure 17. ADN4690E Receiver Output Eye Pattern (Data Rate = 100 Mbps, PRBS  $2^{15} - 1$ ,  $C_L = 15$  pF)

# TEST CIRCUITS AND SWITCHING CHARACTERISTICS

### **DRIVER VOLTAGE AND CURRENT MEASUREMENTS**

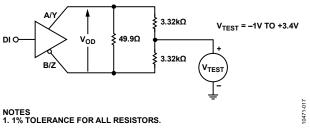
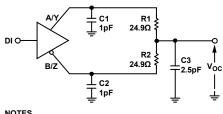


Figure 18. Driver Voltage Measurement over Common-Mode Range



- NOTES
  1. C1, C2, AND C3 ARE 20% AND INCLUDE PROBE/STRAY
  CAPACITANCE < 2cm FROM DUT.
  2. R1 AND R2 ARE 1%, METAL FILM, SURFACE MOUNT, <2cm FROM DUT.

Figure 19. Driver Common-Mode Output Voltage Measurement

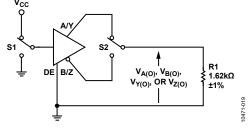


Figure 20. Maximum Steady-State Output Voltage Measurement

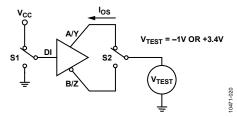
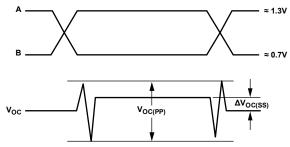


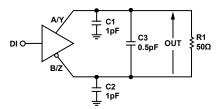
Figure 21. Driver Short Circuit



- 1. INPUT PULSE GENERATOR: 1MHz; 50%  $\pm$  5% DUTY CYCLE;  $t_R$ ,  $t_F \le 1$ ns. 2.  $V_{OC(PP)}$  MEASURED ON TEST EQUIPMENT WITH –3dB BANDWIDTH  $\ge 1$ GHz.

Figure 22. Driver Common-Mode Output Voltage (Steady State)

#### **DRIVER TIMING MEASUREMENTS**

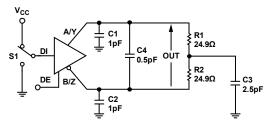


- 1. C1, C2, AND C3 ARE 20% AND INCLUDE PROBE/STRAY CAPACITANCE < 2cm FROM DUT.
  2. R1 IS 1%, METAL FILM, SURFACE MOUNT, <2cm FROM DUT.

Figure 23. Driver Timing Measurement

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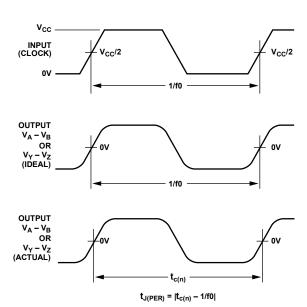
10471



#### NOTES

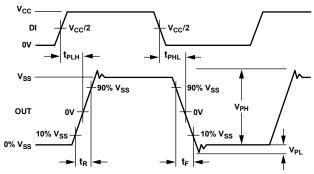
- 1. C1, C2, C3, AND C4 ARE 20% AND INCLUDE PROBE/STRAY
- CAPACITÁNCE < 2cm FROM DUT.
  2. R1 AND R2 ARE 1%, METAL FILM, SURFACE MOUNT, <2cm FROM DUT

Figure 24. Driver Enable/Disable Time Test Circuit



- 1. INPUT PULSE GENERATOR: AGILENT 8304A STIMULUS SYSTEM; 50MHz; 50% ± 1% DUTY CYCLE.
  2. MEASURED USING TEK TDS6604 WITH TDSJIT3 SOFTWARE.

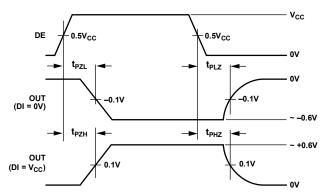
Figure 25. Driver Period Jitter Characteristics



NOTES

- 1. INPUT PULSE GENERATOR: 1MHz; 50%  $\pm$  5% DUTY CYCLE;  $t_R$ ,  $t_F \le$  1ns. 2. MEASURED ON TEST EQUIPMENT WITH -3dB BANDWIDTH  $\ge$  1GHz.

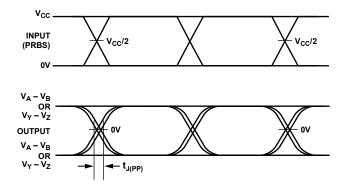
Figure 26. Driver Propagation, Rise/Fall Times, and Voltage Overshoot



NOTES

- 1. INPUT PULSE GENERATOR: 1MHz; 50%  $\pm$  5% DUTY CYCLE;  $t_R$ ,  $t_F \le 1$ ns. 2. MEASURED ON TEST EQUIPMENT WITH -3dB BANDWIDTH  $\ge 1$ GHz.

Figure 27. Driver Enable/Disable Times



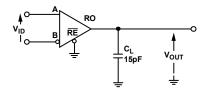
#### NOTES

- INPUT PULSE GENERATOR: AGILENT 8304A STIMULUS SYSTEM; 100Mbps; 2<sup>15</sup> 1PRBS.
- 2. MEASURED USING TEK TDS6604 WITH TDSJIT3 SOFTWARE.

Figure 28. Driver Peak-to-Peak Jitter Characteristics

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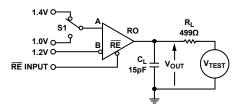
### RECEIVER TIMING MEASUREMENTS



NOTES

1. C<sub>L</sub> IS 20%, CERAMIC, SURFACE MOUNT, AND INCLUDES PROBE/STRAY CAPACITANCE < 2cm FROM DUT.

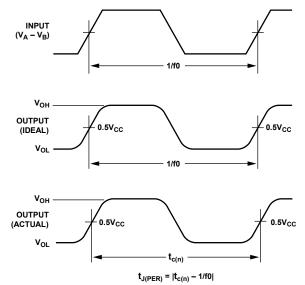
Figure 29. Receiver Timing Measurement



NOTES

- 1. C<sub>L</sub> IS 20% AND INCLUDES PROBE/STRAY
- CAPACITANCE < 2cm FROM DUT.
  2. R<sub>L</sub> IS 1% METAL FILM, SURFACE MOUNT, <2cm FROM DUT.

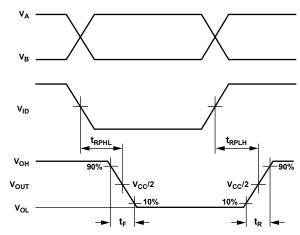
Figure 30. Receiver Enable/Disable Time Test Circuit



#### NOTES

- 1. INPUT PULSE GENERATOR: AGILENT 8304A STIMULUS SYSTEM;
- 50 MHz;  $50\% \pm 1\%$  DUTY CYCLE. 2. MEASURED USING TEK TDS6604 WITH TDSJIT3 SOFTWARE.

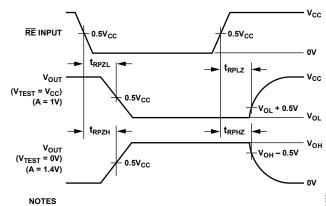
Figure 31. Receiver Period Jitter Characteristics



NOTES

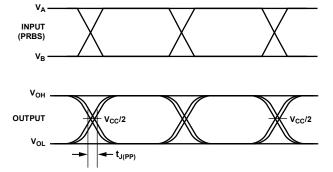
- 1. INPUT PULSE GENERATOR: 1MHz; 50%  $\pm$  5% DUTY CYCLE;  $t_R$ ,  $t_F \le 1 ns$ . 2. MEASURED ON TEST EQUIPMENT WITH –3dB BANDWIDTH  $\ge 1 GHz$ .

Figure 32. Receiver Propagation and Rise/Fall Times



1. INPUT PULSE GENERATOR: 1MHz; 50%  $\pm$  5% DUTY CYCLE;  $t_R$ ,  $t_F \le 1$ ns.

Figure 33. Receiver Enable/Disable Times



- 1. INPUT PULSE GENERATOR: AGILENT 8304A STIMULUS SYSTEM; 100Mbps; 2<sup>15</sup> 1PRBS.
- 2. MEASURED USING TEK TDS6604 WITH TDSJIT3 SOFTWARE.

Figure 34. Receiver Peak-to-Peak Jitter Characteristics

### THEORY OF OPERATION

The ADN4690E/ADN4692E are transceivers for transmitting and receiving multipoint, low voltage differential signaling (M-LVDS) at high speed (data rates up to 100 Mbps). Each device has a differential line driver and a differential line receiver, allowing each device to send and receive data.

Multipoint LVDS expands on the established LVDS low voltage differential signaling method by allowing bidirectional communication between more than two nodes. Up to 32 nodes can be connected on an M-LVDS bus.

#### HALF-/FULL-DUPLEX OPERATION

Half-duplex operation allows a transceiver to transmit or receive, but not both at the same time. However, with full-duplex operation, a transceiver can transmit and receive simultaneously. The ADN4690E is a half-duplex device in which the driver and the receiver share differential bus terminals. The ADN4692E is a full-duplex device that has dedicated driver output and receiver input pins. Figure 36 and Figure 37 show typical half- and full-duplex bus topologies, respectively, for M-LVDS.

#### **THREE-STATE BUS CONNECTION**

The outputs of the device can be placed in a high impedance state by disabling the driver or receiver. This allows several driver outputs to be connected to a single M-LVDS bus. Note that, on each bus line, only one driver can be enabled at a time, but many receivers can be enabled at the same time.

The driver can be enabled or disabled using the driver enable pin (DE). DE enables the driver outputs when taken high; when taken low, DE puts the driver outputs into a high impedance state. Similarly, an active low receiver enable pin  $(\overline{RE})$  controls the receiver. Taking this pin low enables the receiver, whereas taking it high puts the receiver outputs into a high impedance state.

Truth tables for driver and receiver output states under various conditions are shown in Table 9, Table 10, and Table 11.

#### **TRUTH TABLES**

**Table 8. Truth Table Abbreviations** 

Abbreviation	Description
Н	High level
L	Low level
Χ	Don't care
1	Indeterminate
Z	High impedance (off)
NC	Disconnected

### Driver, Half Duplex (ADN4690E)

Table 9. Transmitting (see Table 8 for Abbreviations)

	Inputs		Outputs		
Power	DE	DI	Α	В	
Yes	Н	Н	Н	L	
Yes	Н	L	L	Н	
Yes	Н	NC	L	Н	
Yes	L	X	Z	Z	
Yes	NC	X	Z	Z	
≤1.5 V	Χ	X	Z	Z	

#### **Driver, Full Duplex (ADN4692E)**

Table 10. Transmitting (see Table 8 for Abbreviations)

	Inputs		Outputs	
Power	DE	DI	Y	Z
Yes	Н	Н	Н	L
Yes	Н	L	L	Н
Yes	Н	NC	L	Н
Yes	L	X	Z	Z
Yes	NC	X	Z	Z
≤1.5 V	Χ	X	Z	Z

Type 1 Receiver (ADN4690E/ADN4692E)

Table 11. Receiving (see Table 8 for Abbreviations)

	Inputs	Output	
Power	A – B	RE	RO
Yes	≥50 mV	L	Н
Yes	≤-50 mV	L	L
Yes	-50  mV < A - B < +50  mV	L	1
Yes	NC	L	1
Yes	X	Н	Z
Yes	X	NC	Z
No	X	Χ	Z

#### **GLITCH-FREE POWER-UP/POWER-DOWN**

To minimize disruption to the bus when adding nodes, the M-LVDS outputs of the device are kept glitch-free when when the device is powering up or down. This feature allows insertion of devices onto a live M-LVDS bus because the bus outputs are not switched on before the device is fully powered. In addition, all outputs are placed in a high impedance state when the device is powered off.

#### **FAULT CONDITIONS**

The ADN4690E/ADN4692E contain short-circuit current protection that protects the part under fault conditions in the case of short circuits on the bus. This protection limits the current in a fault condition to 24 mA at the transmitter outputs for short-circuit faults between -1 V and +3.4 V. Any network fault must be cleared to avoid data transmission errors and to ensure reliable operation of the data network and any devices that are connected to the network.

#### RECEIVER INPUT THRESHOLDS/FAIL-SAFE

The Type 1 receivers of the ADN4690E/ADN4692E incorporate 25 mV of hysteresis. This ensures that slow-changing signals or a loss of input does not result in oscillation of the receiver output.

Type 1 receiver thresholds are ±50 mV, so the state of the receiver output is indeterminate if the differential between A and B is about 0 V. This state occurs if the bus is idle (approximately 0 V on both A and B) with no drivers enabled on the attached nodes.

The different receiver thresholds are illustrated in Figure 35. See Table 11 for receiver output states under various conditions.

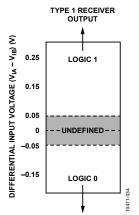


Figure 35. Input Threshold Voltages

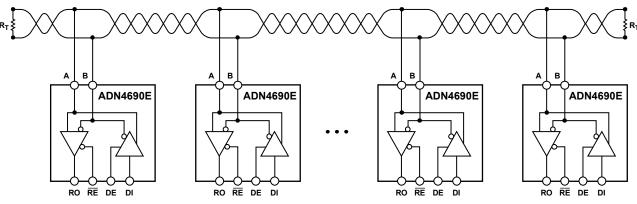
## APPLICATIONS INFORMATION

M-LVDS extends the low power, high speed, differential signaling of LVDS (low voltage differential signaling) to multipoint systems where multiple nodes are connected over short distances in a bus topology network.

With M-LVDS, a transmitting node drives a differential signal across a transmission medium such as a twisted pair cable. The transmitted differential signal allows other receiving nodes connected along the bus to detect a differential voltage that can then be converted back into a single-ended logic signal by the receiver.

The communication line is typically terminated at both ends by resistors ( $R_T$ ), the value of which is chosen to match the characteristic impedance of the medium (typically 100  $\Omega$ ).

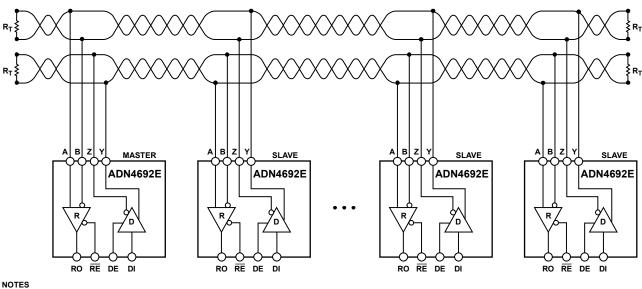
For half-duplex multipoint applications such as the one shown in Figure 36, only one driver can be enabled at any time. Full-duplex nodes allow a master slave topology, as shown in Figure 37. In this configuration, a master node can concurrently send and receive data to/from slave nodes. At any time, only one slave node can have its driver enabled to concurrently transmit data back to the master node.



NOTES

- 1. MAXIMUM NUMBER OF NODES: 32.
- 2.  $R_{\mathsf{T}}$  IS EQUAL TO THE CHARACTERISTIC IMPEDANCE OF THE CABLE USED.

Figure 36. ADN4690E Typical Half-Duplex M-LVDS Network (Type 1 Receivers with Hysteresis)

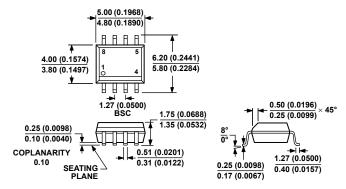


1. MAXIMUM NUMBER OF NODES: 32.

2.  $R_{\mathsf{T}}$  IS EQUAL TO THE CHARACTERISTIC IMPEDANCE OF THE CABLE USED.

Figure 37. ADN4692E Typical Full-Duplex M-LVDS Master-Slave Network (Type 1 Receivers with Hysteresis)

# **OUTLINE DIMENSIONS**

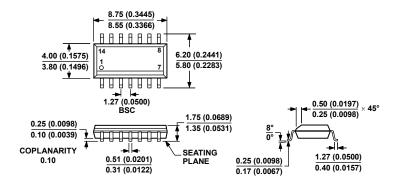


COMPLIANT TO JEDEC STANDARDS MS-012-AA

CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 38. 8-Lead Standard Small Outline Package [SOIC\_N] Narrow Body (R-8)

Dimensions shown in millimeters and (inches)



COMPLIANT TO JEDEC STANDARDS MS-012-AB
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 39. 14-Lead Standard Small Outline Package [SOIC\_N]

Narrow Body

(R-14)

Dimensions shown in millimeters and (inches)

#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range Package Description		Package Option		
ADN4690EBRZ	-40°C to +85°C	8-Lead Standard Small Outline Package (SOIC_N)	R-8		
ADN4690EBRZ-RL7	-40°C to +85°C	8-Lead Standard Small Outline Package (SOIC_N)	R-8		
ADN4692EBRZ	-40°C to +85°C	14-Lead Standard Small Outline Package (SOIC_N)	R-14		
ADN4692EBRZ-RL7	-40°C to +85°C	14-Lead Standard Small Outline Package (SOIC_N)	R-14		
EVAL-ADN469xEHDEBZ		Evaluation Board for Half-Duplex M-LVDS (ADN4690E)			
EVAL-ADN469xEFDEBZ		Evaluation Board for Full-Duplex M-LVDS (ADN4692E)			

<sup>&</sup>lt;sup>1</sup> Z = RoHS Compliant Part.

ADN4690E/ADN4692E

**Data Sheet**